

4/13/26

Exam next Wednesday. Covers through 5.3. (What we cover of it.)

Do part of § 5.3.

We've seen lots of lin transfs and studied the geometry of some.

Def A lin transf $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is orthogonal if it preserves the length of vectors, i.e.

$$\|T(\vec{x})\| = \|\vec{x}\| \quad \forall \vec{x} \in \mathbb{R}^n$$

we'll see other, equivalent, characterizations

The corresp matrix is an orthogonal matrix.

Ex $A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ defines a rotation in $\mathbb{R}^2$ so the

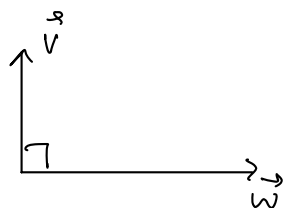
corresp T is orthogonal.

Th (5.3.2) Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be an orthog linear transf. If $\vec{v}$ and $\vec{w}$ are orthog. Then so are $T(\vec{v})$ and $T(\vec{w})$.

so it not only preserves length, it also preserves orthogonality.

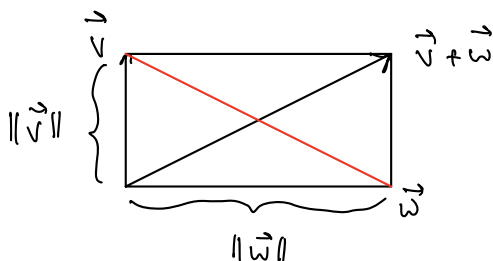
Pf we start with

(Actually preserves angles)



(not necessarily the same length)

These define a rectangle. Note diagonals have the same length



$$\Rightarrow \boxed{\|\vec{v}\|^2 + \|\vec{w}\|^2 = \|\vec{v} + \vec{w}\|^2} \quad (\text{Pythagoras}). \quad \text{This holds because } \vec{v}, \vec{w} \text{ are orthogonal.}$$

To show $T(\vec{v}), T(\vec{w})$ are orthogonal, we need to show

$$\boxed{\|T(\vec{v})\|^2 + \|T(\vec{w})\|^2 = \|T(\vec{v}) + T(\vec{w})\|^2} \quad (*)$$

Let's do that.

Since T is linear, $T(\vec{v} + \vec{w}) = T(\vec{v}) + T(\vec{w})$. So

$$\begin{aligned} \|T(\vec{v}) + T(\vec{w})\|^2 &= \|T(\vec{v} + \vec{w})\|^2 \\ &= \|\vec{v} + \vec{w}\|^2 \quad (T \text{ is orthog. so it preserves length.}) \\ &= \|\vec{v}\|^2 + \|\vec{w}\|^2 \quad (\text{see above}) \\ &= \|T(\vec{v})\|^2 + \|T(\vec{w})\|^2 \quad (\text{again b/c } T \text{ is orthog.}) \end{aligned}$$

This is $(*)$, so we're done. //

thm (5.3.3)

(a) $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is orthogonal iff $T(\vec{e}_1), \dots, T(\vec{e}_n)$ form an orthonormal basis of $\mathbb{R}^n$

(b) An $n \times n$ matrix A is orthogonal iff its columns form an orthonormal basis of $\mathbb{R}^n$.

Note (b) follows from (a) and Th 2.1.2 : $A = \begin{bmatrix} T(\vec{e}_1) & \dots & T(\vec{e}_n) \end{bmatrix}$

I'll leave it to you to read pf of (a). //

Ex $A = \frac{1}{2} \begin{bmatrix} 1 & -1 & -1 & -1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 \end{bmatrix}$

A is orthogonal - check cols are orthonormal

So to check if a matrix is orthogonal, you don't have to check that it preserves lengths. Just check the columns! Sometimes shortens things.

Thm 3.4

If A and B are orthogonal then

- AB is orthogonal
- A^{-1} is orthogonal

pf/ Think about preserving length. leave details to you. //

Def let A be an $m \times n$ matrix.

The transpose of A , A^T , is the $n \times m$ matrix obtained by reversing the roles of rows + columns:

$$A = \begin{bmatrix} \text{--- row 1 ---} \\ \text{--- row 2 ---} \\ \vdots \\ \text{--- row } m \text{ ---} \end{bmatrix}$$

$$A^T = \begin{bmatrix} | & | & & | \\ \vdots & \vdots & \dots & \vdots \\ 1 & 2 & & m \\ | & | & & | \end{bmatrix}$$

A square matrix is symmetric if $A = A^T$

Ex $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \quad A^T = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}$

Ex $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \quad A^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$

Ex $\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix}$ is symmetric.

Now assume A is square. Note

dot prod matrix mult.

$$\vec{x} \cdot \vec{y} = \vec{x}^T \vec{y}$$

Say $A = \begin{bmatrix} \vec{v}_1 & | & \vec{v}_2 & | & \dots & | & \vec{v}_n \end{bmatrix}$

so $A^T = \begin{bmatrix} \vec{v}_1^T \\ \hline \vec{v}_2^T \\ \hline \vdots \\ \hline \vec{v}_n^T \end{bmatrix}$

Then

$$A^T A = \begin{bmatrix} \vec{v}_1^T \\ \vec{v}_2^T \\ \vdots \\ \vec{v}_n^T \end{bmatrix} \begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_n \end{bmatrix}$$

$$= \begin{bmatrix} \vec{v}_1 \cdot \vec{v}_1 & \vec{v}_1 \cdot \vec{v}_2 & \dots & \vec{v}_1 \cdot \vec{v}_n \\ \vdots & \vdots & & \vdots \\ \vec{v}_n \cdot \vec{v}_1 & \vec{v}_n \cdot \vec{v}_2 & \dots & \vec{v}_n \cdot \vec{v}_n \end{bmatrix}$$

Thm 5.3.7 (This is important.)

Let A be an $n \times n$ matrix. Then A is orthogonal iff $A^T A = I_n$,

ie iff $A^T = A^{-1}$.

pf/

A is orthogonal iff the columns $\vec{v}_i$ form an orthonormal basis

(5.3.3)

$$\text{iff } \begin{aligned} \vec{v}_i \cdot \vec{v}_i &= 1 & \forall i \\ \vec{v}_i \cdot \vec{v}_j &= 0 & \forall i \neq j \end{aligned}$$

$$\text{iff } A^T A = I_n //$$

See Summary 5.3.8 about orthogonal matrices

key additional fact:
orthogonal lin. transf.
preserve dot products, hence
angles, not only orthogonality.
See below.

See Th 5.3.9 for a summary of basic facts about transposes